

AE461 presentation

Members:

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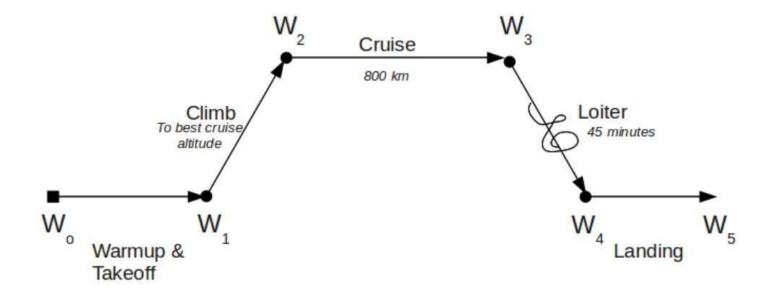
> Instructed by- Mr. A.K Ghosh Mr. D.K Giri

Mission Requirements

- 1. Weight of aircraft < 1500kg
- 2. Number of passengers = 4. Assume 1 crew + luggage(10kg bag per each)
- 3. Design cruise speed 50-70m/s
- 4. Stall speed(steady straight level flight) 30-40m/s
- 5. Absolute ceiling(height from mean sea level) -10,000ft
- 6. Rate of climb at mean sea level = 4-8m/s
- 7. Able to fly at minimum drag as well as minimum power. Therefore $V_{cruise_{P_{min}}} < V_{cruise_{D_{min}}}$
- 8. Endurance Greater than 4 hours
- 9. Range More than 1000 km (for round trip, 2000km)
- 10. Landing distance 400-600m
- 11. Take-off distance 300-500m
- 12. Service ceiling 7km

Also we assume that we are dealing with a low speed air-craft and neutral position of control surfaces at design cruise speed.

Step 1. Mission profile



- Take-off : 0-1
- Climb 1-2
- Cruise 3-4
- Loiter 3-4
- Landing 4-5

Step – 2 Weight Estimation

- Types of weight
 - a) Weight of crew $W_{crew} = W_c$
 - b) Weight of payload $W_{payload} = W_p$
 - c) Weight of fuel $W_{fuel} = W_f$
 - d) Empty weight of aircraft $W_{empty} = W_e$
- Design take-off gross weight $W_0 = W_c + W_p + W_f + W_e$
- We define gross weight because actual weight changes due to fuel consumption
- First estimate of W_0 is made by transforming the gross-weight equation as follows

$$W_0 = \frac{W_c + W_p}{1 - \frac{W_f}{W_0} - \frac{W_e}{W_0}}$$

• This expression is useful as we can readily obtain ratios $\frac{W_f}{W_0}$ and $\frac{W_e}{W_0}$

Step 2.1 Estimation of $\frac{W_e}{W_0}$

- Aircraft design is evolutionary. So statistical/historical data provides a starting point for conceptual design of a new aircraft.
- From Fig. 8.1 Ch-8 Airplane design in provided notes, $\frac{We}{W_0}$ with gross weight for reciprocating propeller driven airplane is given.
- For 2000-3000kg aircraft $\frac{We}{W_0} = 0.62$
- According to sample calculations provided, ours is an aircraft < 1500kg weight, we can assume W_0 to be in the range 2000-3000 for now. So $\frac{We}{W_0} = 0.62$

Step 2.2 Estimation of $\frac{W_f}{W_0}$

• The factors on which amount of fuel depends are mainly efficiency of propulsion device and aerodynamic efficiency. These are included in the *Brequet Range equation :-*

$$R = \frac{\eta_{pr}}{c} \left(\frac{L}{D}\right) \ln \left(\frac{W_0}{W_f}\right)$$

- For i^{th} mission segment, weight fraction = $\frac{Wi}{W_{i-1}}$.
- <u>Weight of airplance at end of mission</u> $= \frac{W_5}{W_0} = \frac{W_1}{W_0} \times \frac{W_2}{W_1} \times \frac{W_3}{W_2} \times \frac{W_4}{W_3} \times \frac{W_5}{W_4}$

Also $W_f = W_0 - W_5 \rightarrow \frac{W_f}{W_0} = 1 - \frac{W_5}{W_0}$. Allowing 6% allowance for reserve fuel and trapped fuel, $\frac{W_f}{W_0} = 1.06 \left(1 - \frac{W_5}{W_0}\right)$

• For 0-1 segment, historical data shows $\frac{W_1}{W_0} \approx 0.97$. For 1-2 segment, also historical data shows $\frac{0}{W_1} = 0.985$

For 2-3 segment, we'll use Brequet range equation. For this <u>L</u> estimated is needed. At this stage of design, we haven't laid out shape of airplane. So making an assumption based on existing airplanes –

Airplane	$\begin{pmatrix} \boldsymbol{L} \\ \boldsymbol{\overline{D}} \end{pmatrix}_{max}$
Cessna 310	13.0
Beach Bananza	13.8
Cessna Cardinal	14.2

So a reasonable estimate $\left(\frac{L}{D}\right)_{max} \approx 13.5$

- Typical value of $\eta_{pr} \approx 0.85$. Now $R = \frac{\eta_{pr}}{c} \left(\frac{L}{D}\right) \ln \left(\frac{W_2}{W_3}\right)$ where $c = 6.27 \times 10^{-7} m^{-1}$
- We are given R = 1000km. So, performing the calculations, $\frac{W2}{W_3} = 1.059$
- For segment 3-4, ignoring details of fuel consumption, ^{W4}/_{W3} = 1. For segment 4-5, during landing according to historical data ^{W5}/_{W4} = 0.995
 Now, ^{W5}/_{W0} = ^{W1}/_{W0} × ^{W2}/_{W1} × ^{W3}/_{W2} × ^{W4}/_{W3} × ^{W5}/_{W4} = 0.97 × 0.985 × ··· ≈ 0.897
 Therefore, ^{Wf}/_{W0} = 1.06 (1 ^{W5}/_{W0}) = 0.1092

Step 2.3 - Calculation of W_0

• Assumed average weight of a person is 75kg

•
$$W_p = 75 + 10 \times 4 = 340 kg$$

• $W_0 = \frac{W_c + W_p}{1 - \frac{W_f}{W_0} - \frac{W_e}{W_0}} = 1427 kg. W_f = 155.83 kg$

Step 3 – Sizing of the wing

• For steady straight level flight W = L (weight = lift)

•
$$W = \frac{1}{2} \rho V^2 S C_l \rightarrow \frac{W}{S} = \frac{1}{2} \rho V^2 C_l$$

• $W = \frac{1}{2}^2 \rho V_{stall} C_{l_{max}}$ is called wing loading and $C_l = \text{lift coefficient}$
• Taking $V_{stall} = 30m/s$ from mission requirements and $C_{l_{max}} = 2.3$ at takeoff. $\frac{W}{S} = \frac{126787N}{m^2} = 129.24kg/m^2$

Wing loading at desired cruise speed and lift coefficient

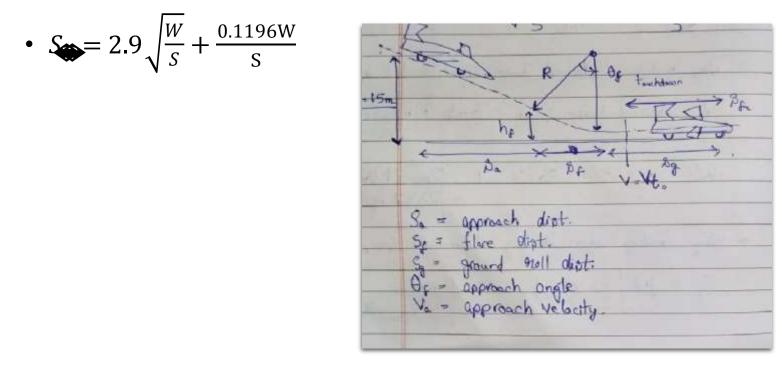
• V = desired cruise speed = 70m/s and = 0.4 from mission requirements.

•
$$\frac{W}{S} = \frac{1}{2}(1.225)(70)^2 \times 0.4 = \frac{12005N}{m^2} = 122.37kg/m^3$$

Wing loading when landing distance is specified

•
$$S_{m} = jN \sqrt{\frac{2}{\rho_{\infty}} \times \frac{W}{S} \times \frac{1}{C_{l_{max}}}} + \frac{\frac{j^2 W}{S}}{g\rho_{\infty} C_{l_{max}} \mu_r}$$

• j = 1.15 for commercial airplanes, N = 3s (time increment for free roll immediately after touchdown) and $\mu = 0.4$



• Now,
$$S_g = S_l - S_a - S_f$$

• $\theta_a = \theta_f$, obstacle length = 15m and $S_f = Rsin\theta_f$, $h_f = R$ $(1 - cos\theta_a)$
• $S_{\bullet \bullet} = S - \frac{15 - h_f}{\tan \theta_f} - Rsin\theta_f$. Taking $R = \frac{V_f^2}{2g}$ and $\psi_f = 1.23 \times V_{sta}$, $R = 693.99m$

•
$$S_g = 195.61m$$

• Now,
$$195.61 = 2.9 \sqrt{\frac{W}{S} + \frac{0.1196W}{S}}$$
. Taking $\frac{W}{S} = t^2$ and solving the resultant quadratic equation, $\frac{W}{S} = 902.75N/m^2 = 92kg/m^2$

• So, • $\frac{W}{S}_{stall conditions} = 129.24 kg/m^2$ $= 122.37 kg/m^2$ *S*[¬]*cruise velocity approximation* • $\frac{W}{S}$ landing approach $=\frac{92kg}{m^2}$ is off from other two values. If we choose S = 550m, then • W S landing approach repeating the calculations, we get $\frac{W}{s} = 1209.82N/m^2 = \frac{123.32kg}{m^2}$ • Now we can see that all the three values are close to each other. • To find the area of wing, $S = \frac{W}{\left(\frac{W}{S}\right)} = \frac{1427}{122.37} = 11.66m^2$ • Let aspect ratio AR of wing be 10. Then $AR = 10 = \frac{b^2}{2}$ • Wing span, $b = \sqrt{10 \times 11.66} = 10.798m$ • Wing chord, $c = \frac{b}{AR} = \frac{10.798}{10} \approx 1.08$

Step 4 – Power Requirements

Calculating cruise power required at different altitudes

$$\left(\frac{R}{C}\right)_{\max} = \left(\frac{n_{p_r}p}{w}\right) - \left(\frac{2}{\rho_{\infty}}\sqrt{\frac{K}{3C_{D_0}}}\frac{w}{s}\right)^{1/2} \frac{1.155}{\left(\frac{L}{D}\right)_{\max}}$$

- $\rho = 1.225$
- $(R/C)_{max} = 2m/s, 4m/s, 6m/s, 8m/s, 10m/s$
- $C_{Do} = 0.035$
- W/S = 129.37×9.81
- K = 0.075
- $W=W_o = 1404.96 \times 9.8N$

 $\eta_{pr}P/W = 0.8\rho/(1404.96 \times 9.81)$ P = 1404.96×9.81/0.8 [(R/C) _{max}+ 3.399]

$$(R/C)_{max} = 2m/s , P = 124.68 hp$$

$$(R/C)_{max} = 4m/s , P = 170.87 hp$$

$$(R/C)_{max} = 6m/s , P = 217.06 hp$$

$$(R/C)_{max} = 10m/s , P = 309.44 hp$$

Step 5 – Tail Design

• Step 5.1:

$$(C_L)_{design} = 0.5$$

Static margin , sm = 15% = 0.15

as, sm =
$$-\frac{dC_m}{dC_L}$$

 C_{Mo} = 0.075

$$C_{L_{\omega}} = C_{L_0} + L_{L_{\alpha_{\omega}}} \alpha$$

Airfoil – $C_{L_0w} = 0.2084 , C_{L_\alpha} = 5.9/\text{rad} , c_{ma_c} = -0.08$ $C_{m_0w} = 0.03126$

Aspect ratio(AR) = 10(approx) and e = 0.8

$$(C_{L_{\alpha}})_{\omega ing} = \frac{C_{L_{\alpha}}}{1 + \frac{C_{L_{\alpha}}}{\pi e A R}}$$

$$C_{L_{a_W}} = \frac{\frac{5.9}{\pi eAR + 5.9}}{\pi eAR}$$

$$=4.778\times2.5\times\pi/100=0.2084$$

$$(C_{m_{ac}})$$
wing = $(C_{m_{ac}})$ airfoil * $\frac{AR}{AR+2}$
= -0.08×10/12
= -0.066

• Main Formula

$$C_{m_{cg}} = C_{M_0} + C_{m_\alpha} \alpha$$

1.
$$c_{m_0} = c_{m_{ac_w}} + c_{L_0w}(x_{cg} - x_{ac}) + V_H \eta c_{L_{o_t}} \{\varepsilon_0 - it\}$$

Type equation here.

2.
$$C_{m_{\alpha}} = C_{L_{\alpha_{W}}}(x_{cg} - x_{ac}) - V_{H}\eta c_{L_{\alpha_{t}}}\left[1 - \frac{d\varepsilon}{d\alpha}\right]$$

Eqn. 1 And 2 should satisfy

 $c_{m_0} = 0.031126$ and static margin = 0.15 $X_{ac} = C/4$ (C= 1.2 our design) $X_{ac} = 0.3$ and $\eta = 0.9$, $V_{H} = 0.6$, $\varepsilon_0 = 0.76^{\circ}$

NACA 0009, --
$$C_{L_{\alpha_t}} = 3.8/\text{rad}$$
 and $c_{L_0} = 0$

• Iteration 1:

Assume $X_{cg} = 0.35 \text{ C}$

Find it in equation 1

 $0.03126 = -0.066 + 0.2084(0.35 - 0.25) + 0.6 \times 0.9 \times 3,8[0.76 - i_t] \times \pi/180$ $i_t^o = -1.734^o$

► Equation 2

$$X_{cg} = X_{NP} \quad \text{as} \quad C_{m_{\alpha}} = 0$$
$$X_{NP} = X_{ac} + \eta V_{H} \frac{C_{L_{\alpha_{t}}}}{C_{L_{\alpha_{w}}}} \left(1 - \frac{d\varepsilon}{d\alpha}\right)$$

$$\frac{d\varepsilon}{d\alpha} = 0.3041$$

$$X_{NP} = 0.25 + 0.2988671$$

 $X_{NP} = 0.5488$

✓ Static margin designed = $X_{cg} - X_{NP} = 0.20$ ✓ Needed (static margin) = 0.15

• Iteration 2:

Assume $X_{cg} = 0.40$ $i_t^{o} = -1.0828^{o}$

► Equation 2

$$C_{m_{\alpha}} = 0$$
$$X_{\rm NP} = 0.549$$

✓ Static margin = $X_{cg} - X_{NP} = 0.15$ (approx)

So finally,

Tail setting
$$i_t = -1.0828^\circ$$

SM = 0.15 and $X_{cg} = 0.4$

Step 6 – The stability derivatives

- (Area) $S = 10.86 \text{ m}^2$
- (Span) B = 10.4 m
- (Aspect ratio) AR = 10
- (Chord) C = 1.05 m
- K = 0.044
- $C_{D_o} = 0.0881$
- $\frac{C_L}{C_D} = 15.5$ (approx)

•
$$\frac{\text{Thickness}}{\text{Chord}} = 12\%$$

We choose NACA – 4412 airfoil

- $(C_L)_{max} = 1.25$
- $\alpha_{stall} = 13$ degree
- $C_{M_o} = -0.098$

•
$$C_1 = 0.4$$

 $\succ C_{L_{\alpha}} = \frac{dC_L}{d\alpha} = 1.8\pi (1+0.8 \text{max/c})$

•
$$C_{L_{\alpha_{2d}}} = 6.198$$

$$\succ C_{L_{\alpha}} = \frac{C_{L_{\alpha_{2d}}}}{1 + \frac{C_{L_{\alpha_{2d}}}}{\pi \cdot AR}} = \frac{6.18}{1 + \frac{6.18}{\pi \cdot 10}}$$

•
$$C_{L_{\alpha}} = 5.164/rad$$

Now,

$$\sum F_{x} = W - L$$
$$\sum L = C_{L_{o}} + C_{L_{\alpha}}\alpha + C_{L_{\delta e}}\delta e$$

Mean value

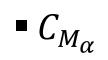
$$\left(\frac{dC_L}{d\alpha}\right)_{\text{mean}} = \frac{s_f}{s} \left(\frac{dc_L}{d\alpha}\right)_f + \left(1 - \frac{s_f}{s}\right) \frac{dc_L}{d\alpha}$$

(f - devotes the flap)

• $C_{D_{\alpha}}$

 $C_{\rm L} = C_{L_{\alpha}} \alpha$ $C_{\rm D} = C_{\rm D_o} + K C_{\rm L}^2$

$$C_{D_{\alpha}} = \left(\frac{dC_{D}}{dC_{L}}\right) \cdot \left(\frac{dc_{L}}{d\alpha}\right)$$
$$C_{D_{\alpha}} = 2\text{K C}_{L} \cdot C_{L_{\alpha}}$$
$$C_{D_{\alpha}} = 2 \times 0.042 \times 0.45 \times 5.164$$
$$C_{D_{\alpha}} = 0.1952$$



$$\sum M = C_{M_o} + C_{M_\alpha} \alpha + C_{M_{\delta e}} \delta e$$

$$C_{M_\alpha} = C_{L_\alpha} (X_{cg} - X_N)$$

$$C_{M_\alpha} = -5.1 \times 0.15$$
Static margin = 0.15

$$C_{M_{lpha}} = -0.765$$

Pitch Rate

> C_{Lq} – Represents change in airplane lift with varying pitching velocity, with α const.

Wing contribution to C_{L_a}

$$\Delta \alpha = \frac{q(X_{cg} - X_{ac})}{U}$$

(X_{cg} means dist. to C.G) (X_{ac} means dist. to A.C)

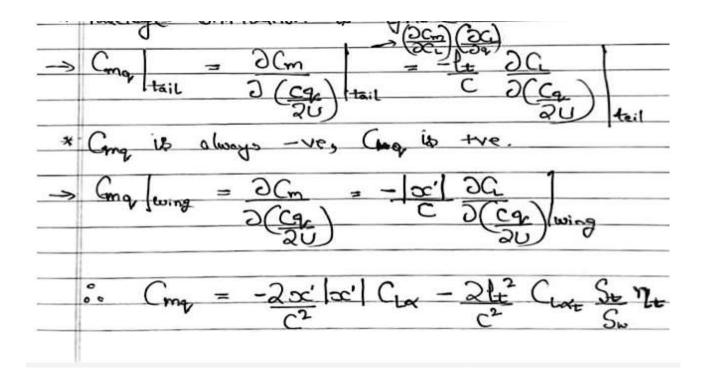
- If a.c is very close to c.g the contribution from wing is negligible
- For light airplanes fuselage contribution to C_{L_q} is smaller than wing, so ignored.

• Wing contribution

$$\frac{\partial C_L}{\partial \frac{c_a}{\partial U}} = \frac{\partial x'}{c} c_{L_\alpha}$$

(x' – distance from c.g to wing chord) ($c_{L_{\alpha}}$ - wing lift slope)

- > C_{Dq} Represents change in drag with varying pitch velocity at constant α .
- For subsonic flight, c_{D_a} is very small and ingnored.
- > C_{Mq} Represents change in pitching moment coefficient due to change in pitching velocity.
- Wing contribution to c_{M_q} either opposes or increases the pitching motion
- Fuselage contribution is ignored.



- Typical value of $c_{L_{\alpha}}$ for light airplane falls in range 4.0 7.0 depending on the type of wing.
- The value of c_{L_q} for 'Cesna 182' is 3.9
- c_{D_q} is chosen to be 0
- c_{M_q} for Cessna 182 = -12.43

-Drawing Layout of Aircraft-

- AR (Aspect ratio) = 10
- S (Area) = 10.86 m^2
- b (wing span) = 10.4m
- C (wing chord) = b/AR = 1.05m
- L_f (Fuselage length) = 70% of wing span = 7.28m

Now,

Data from similar airplane

➢ Horizontal tail

- $S_h/S = 0.03$
- $S_{horiz tail} = 3.36 \text{ m}^2$
- $A_h = 5$
- $b_n = 4.098m$

• $C_h = S/b = 0.82m$

≻ Vertical tail

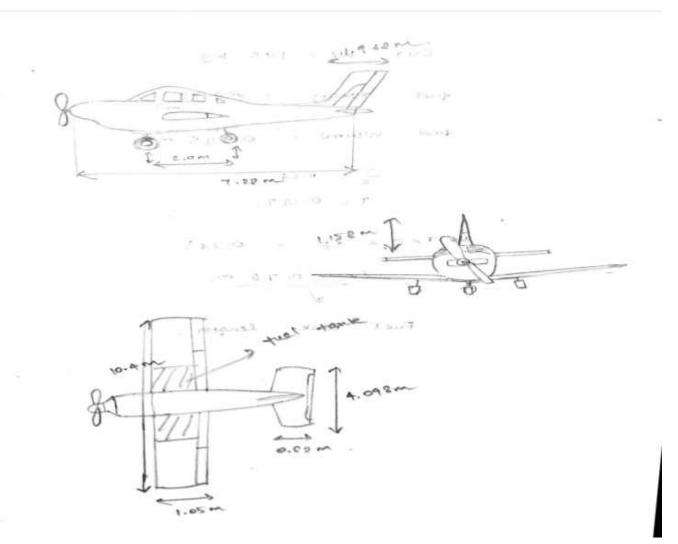
- $S_v/S = 0.21$
- $S_{vertical tail} = 2.28 m^2$
- $A_v = 1.7$
- $b_v = 1.968m$
- $C_v = 1.158m$

➢ Fuel tank

- fuel weight = 195kg
- fuel density = 800 kg/m^3
- fuel volume = 0.245 m^3
- T/c = 0.14
- T = 0.147

 $T \times C \times l_f \times 2 = 0.245$

• $l_f = 0.76m$ (fuel tank length)



TWIN BOOM PUSHER WITH AUTOPILOT

GROUP A

MOTIVATION

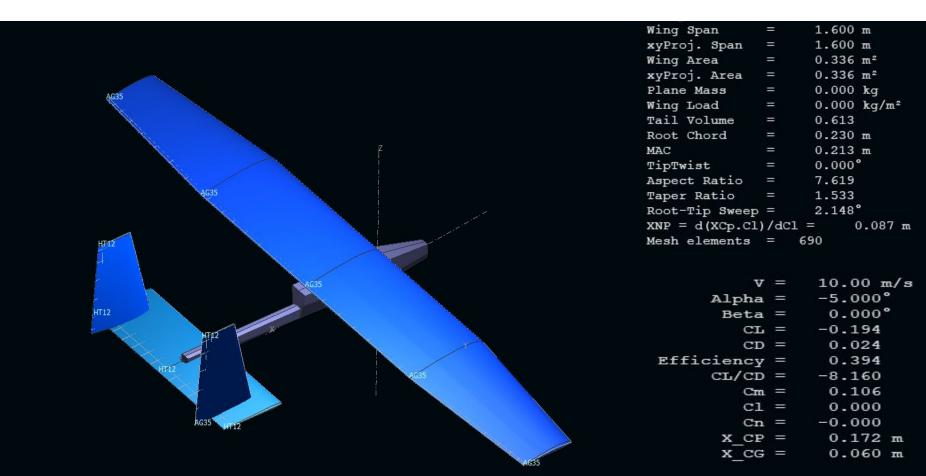
We wanted to do something different, something challenging and something unique. History had the answer. Commemorating the WW1 warbirds!

ABOUT TWIN BOOM AIRCRAFTS

This is an aircraft with two nacelles or longitudinal booms. These booms can be used to carry fuel or can be used for supporting structural mounting. They are generally lighter and smaller, have more structural support to wings, easy in loading/unloading goods.

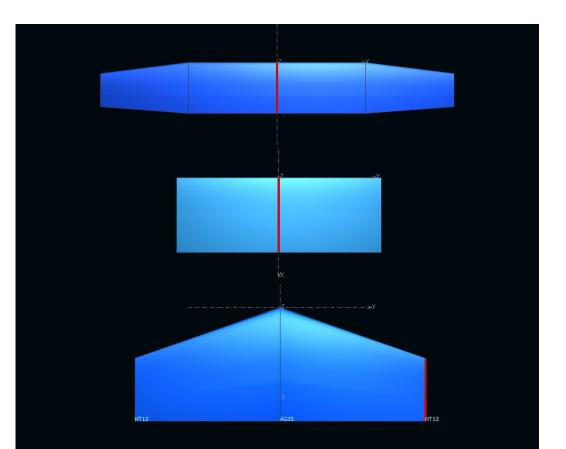






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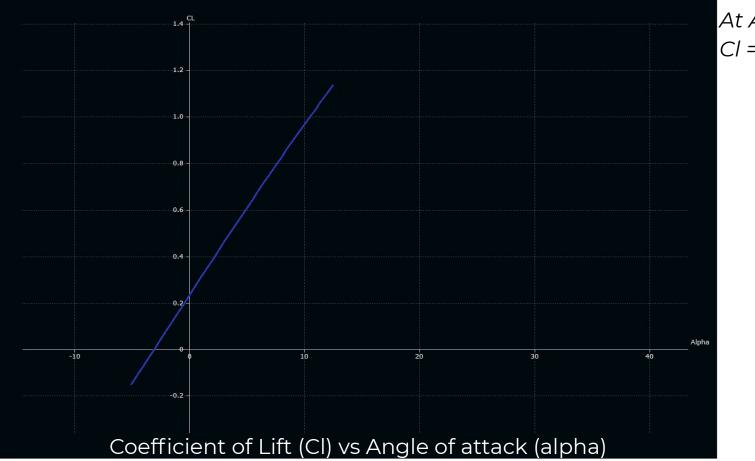


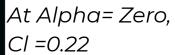


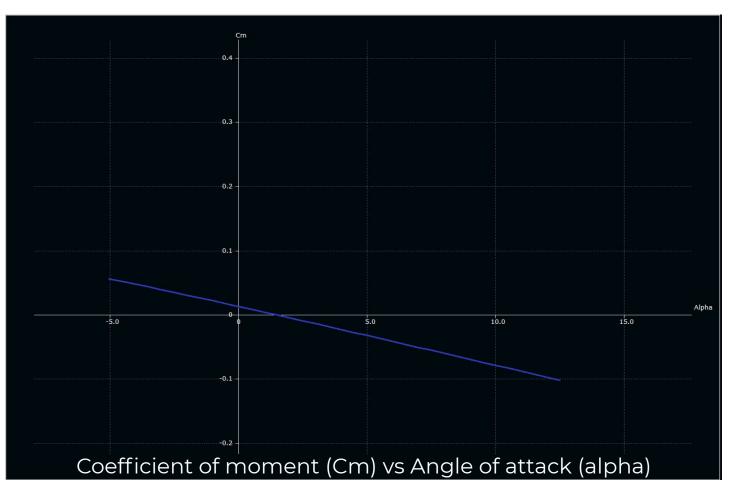
AG35 Airfoil Span = 1.6 m

HT12 Airfoil Span = 0.5 m

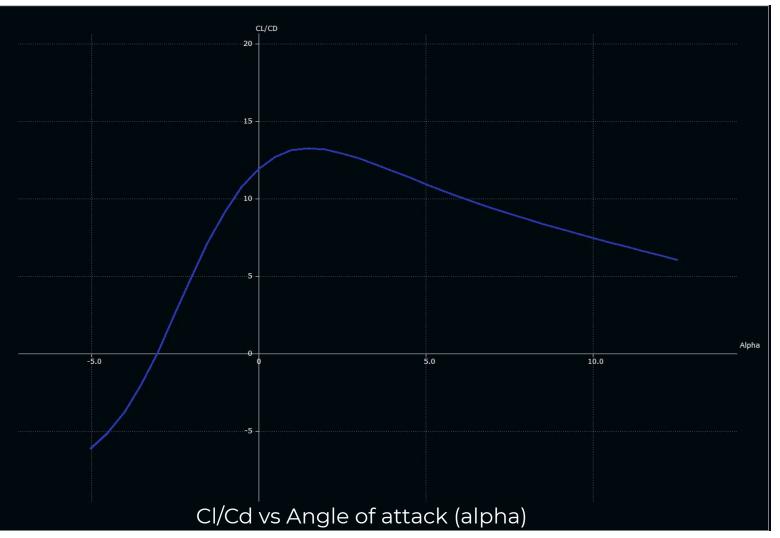
HT12 Airfoil Span = 0.23 m







Trim angle (the angle at which moment is zero)= 2.3⁰

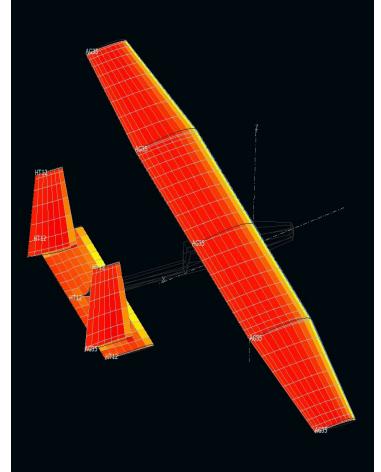


Cl/Cd value is maximum at alpha=2.2⁰

AERODYNAMIC ANALYSIS

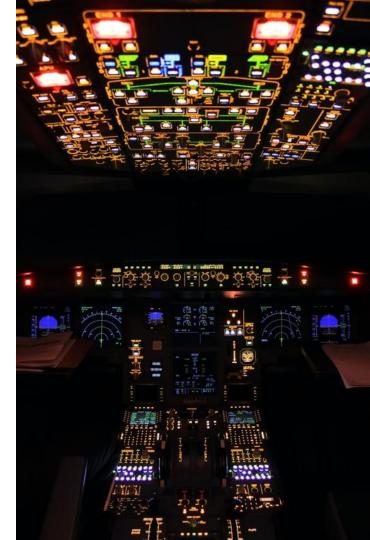
The above-mentioned graphs and plane model were designed and analysed in XFLR5 Software. Aerodynamic points needed to be considered while analysis ar as follows:-

- 1. CG of the model must be ahead (nearer to the nose) of NP, for longitudinal stability that is stability in pitching plane
- 2. The slope of **Cm vs Alpha** graph should be **negative** for aerodynamically stable aircraft
- 3. The **trim angle**(here is 2.3^o) shouldn't be of much higher value.
- The value of alpha in the graph of Cl/Cd vs alpha and Cm vs alpha should be nearly the same, for better stability and efficiency
- 5. The value of CI must be **positive** at $alpha=0^{\circ}$



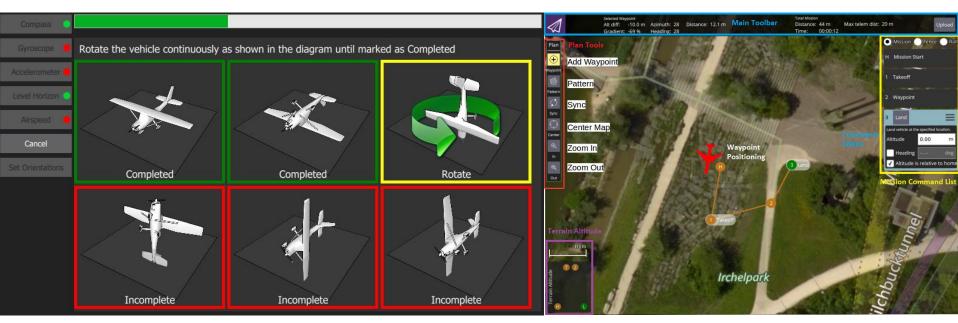
<u>AVIONICS</u>

- 2200 KV BLDC Motor
- 30A ESC
- 7 inch Propeller
- Control Surface Servo
- 3S 2200mAh Battery
- Pixhawk FC
- GPS Sensor
- AirSpeed Sensor
- Telemetry Pair
- Radio Tx/Rx



<u>AUTONOMY</u>





Frame Setup Calibration Parameter Tweaking

Mission Planning

COST ANALYSIS

TOTAL	INR 25,548	
Styrofoam and Monokote	INR 800	
Transmitter & Receiver	INR 7100	
Telemetry Pair 915 MHz	INR 1700	
Airspeed Sensor	INR 2000	
Carbon Rod	INR 2598	
GPS	INR 1800	
Pixhawk with power module	INR 6000	
LiPo Battery	INR 1550	
Servos	INR 400	
Propellers	INR 200	
ESC	INR 500	
Motor	INR 900	



WORK ANALYSIS

Work Done

We cut the parts of the aircraft, wing (in sections), Horizontal and Vertical Tail, with Green Styrofoam.

Proper sanding and cutting have been done.

- Work Planned
 - Lab-1: Fuselage and starting basic assembly.
 - Lab-2: Placing all the electronics, building control surfaces and final assembly. Pixhawk configuration.
 - Lab-3: Covering all the parts with a Monokote sheet.
 - Lab-4: Testing.



<u>GLIDER</u>

A glider model for getting hands-on training in fabrication was made by our group within two and a half labs. This was made of styrofoam where we learned skills like basic fabrication techniques, handling hot wires, sanding, taping and assembly of the model. We learned adjustment of CG and did multiple tests. However the model was damaged and we repaired it before its final flights.



THANK YOU!

Abhijeet	170015
Aditya Raghuvanshi	170052
Amrendra Pratap Singh	170097
Mataria Pence Jagatkumar	170382
Naveen Balaji N	170420